

Phonons in 3D

$$\bar{R}_z = \bar{R}_{n,\alpha} = \bar{R}_n^0 + \bar{R}_\alpha^0 + \bar{u}_{n\alpha}$$

\bar{R}_z → Instantaneous position of atom $L=(n,\alpha)$
 unit cell ← \bar{R}_n^0 ← basis atom
 \bar{R}_α^0 → equilibrium position of unit cell
 $\bar{u}_{n\alpha}$ → displacement of atom from equilibrium
 equilibrium position of basis pt.

Harmonic Approximation:

$$\mathcal{H} = \sum_{n,\alpha} \frac{\bar{P}(n,\alpha)^2}{2M_\alpha} + \sum_{n,n'} \sum_{\alpha,\alpha'} \sum_{\mu,\mu'} \psi_{\alpha,\alpha'}^{\mu,\mu'}(n,n') u_\alpha^\mu(n) u_{\alpha'}^{\mu'}(n')$$

Sum over unit cells $n=0, \dots, N$
 Sum over basis atoms $\alpha=1 \dots N_b$
 Sum over dimensions $\mu=x, y, z$

$\psi_{\alpha,\alpha'}^{\mu,\mu'}(n,n')$ → force induced on the (n,α) atom in the μ -direction, due to a unit displacement of the (n',α') atom in the μ' -direction

→ we can follow the same procedure as before

Once again, we obtain coupled differential equations. Solutions for displacement take the form:

$$u_{\alpha}^m(n, t) = u_{\alpha}^m(n) \frac{1}{\sqrt{M_{\alpha}}} e^{-i\omega t}$$

$$= \frac{e^{i\mathbf{k} \cdot \bar{\mathbf{R}}_n}}{\sqrt{M_{\alpha}}} e^{i\mathbf{k} \cdot \bar{\mathbf{R}}_{\alpha}^0} e^{-i\omega t}$$

geometric phase factor
(depends on position
in lattice)

oscillatory term

- the result is a characteristic eqn defining the Dynamical Matrix:

$$\omega^2 \epsilon_{\alpha}^m = \sum_{\alpha', m'} D_{\alpha, \alpha'}^{m, m'} \epsilon_{\alpha'}^{m'} \Rightarrow \omega^2 \epsilon(\mathbf{k}) = D(\mathbf{k}) \epsilon(\mathbf{k})$$

Dynamical Matrix elements:

$$D_{\alpha, \alpha'}^{m, m'}(\mathbf{k}) = \frac{1}{\sqrt{M_{\alpha} M_{\alpha'}}} \sum_{n'} \psi_{\alpha, \alpha'}^{m, m'}(n, n') e^{i\mathbf{k} \cdot (\bar{\mathbf{R}}_n - \bar{\mathbf{R}}_{n'})}$$

$$m = n - n'$$

$$D_{\alpha, \alpha'}^{m, m'}(\mathbf{k}) = \frac{1}{\sqrt{M_{\alpha} M_{\alpha'}}} \sum_m \psi_{\alpha, \alpha'}^{m, m'}(m) e^{i\mathbf{k} \cdot \bar{\mathbf{R}}_m}$$

- Notice now that $\hat{D}(\mathbf{k})$ is a $3N_b \times 3N_b$ matrix
 $\Rightarrow N_b = \#$ of atoms in unit cell (in basis)

- Evidently, we will have $3N_b$ independent solutions for $\omega^2(\mathbf{k})$, i.e. $3N_b$ phonon branches.

- the terms ϵ_{α}^m represent the amplitude normalization of the vibration.

- in our general equation: $\omega^2 \mathbf{E}(\mathbf{k}) = \hat{D}(\mathbf{k}) \mathbf{E}(\mathbf{k})$:

$$\mathbf{E}(\mathbf{k}) = (\epsilon_1^x, \epsilon_1^y, \epsilon_1^z, \epsilon_2^x, \epsilon_2^y, \epsilon_2^z, \dots, \epsilon_{N_b}^x, \epsilon_{N_b}^y, \epsilon_{N_b}^z)$$

- For each atom type, α , we can write:

$$\bar{\mathbf{E}}_{\alpha}(\mathbf{k}) = (\epsilon_{\alpha}^x, \epsilon_{\alpha}^y, \epsilon_{\alpha}^z)$$

and

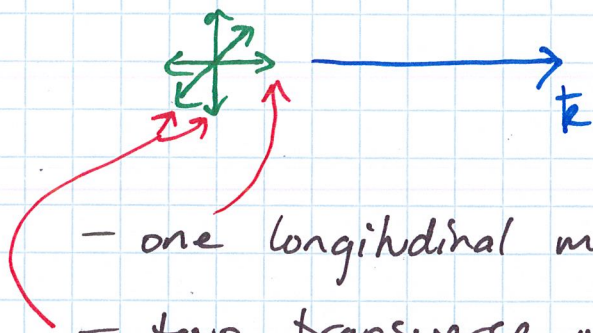
$$\bar{u}_{\alpha}(\mathbf{r}, t) = \frac{\bar{\mathbf{E}}_{\alpha}(\mathbf{k})}{\sqrt{M_{\alpha}}} e^{i\mathbf{k} \cdot (\bar{\mathbf{R}}_{\alpha}^0 + \bar{\mathbf{R}}_{\alpha}^c) - i\omega t}$$

\hookrightarrow displacement vector

- We see here that $\bar{\mathbf{E}}_{\alpha}(\mathbf{k})$ represents the "direction" of oscillation, i.e. polarization of the vibrational mode

$\bar{\mathbf{E}}_{\alpha}(\mathbf{k}) \rightarrow$ polarization vector

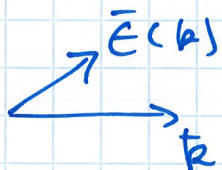
In general, in 3D, oscillations can be \parallel or \perp to \vec{k} :



- one longitudinal mode
- two transverse modes

- Polarization vector $\vec{E}(\vec{k})$ determines the type of mode

- Although, $\vec{E}(\vec{k})$ need not be exclusively transverse or longitudinal:



(2-T & L form
lin. indep. basis for solutions.
Lin. comb. of solutions are
also solutions)

- If there are 2 or more atoms in the unit cell, there will be both optical & acoustic modes:

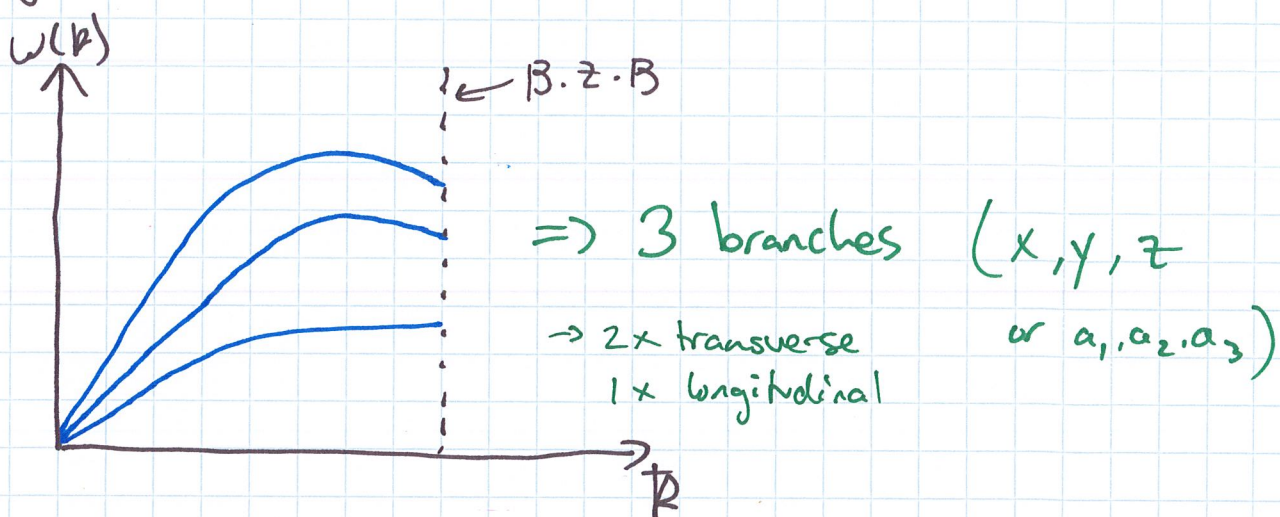
TO : transverse optical

TA : transverse acoustic

LO : longitudinal optical

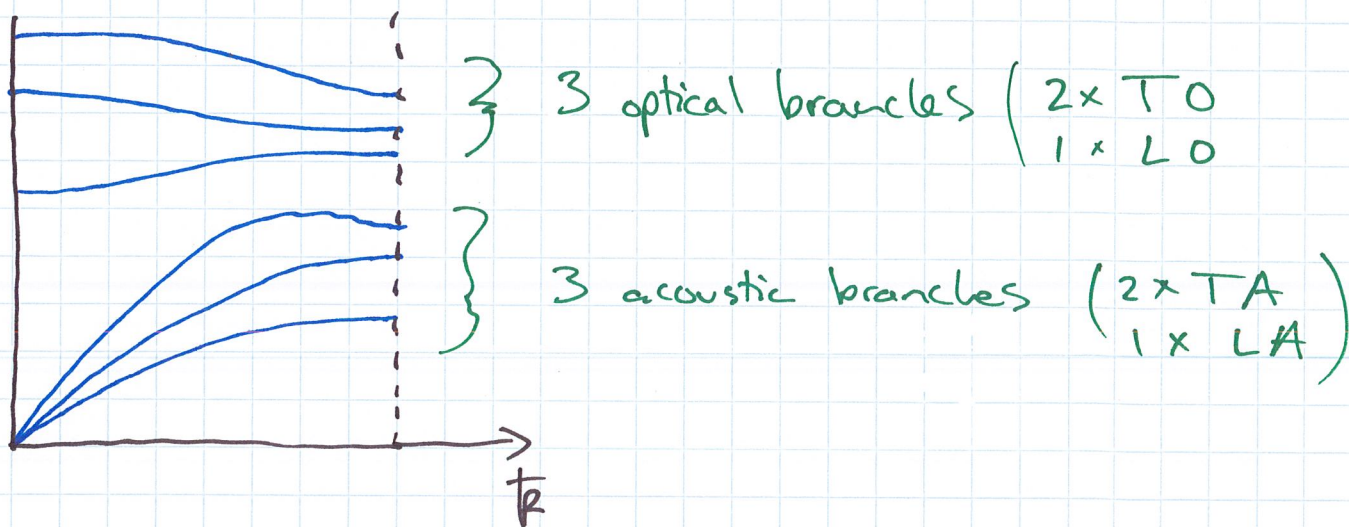
LA : longitudinal acoustic

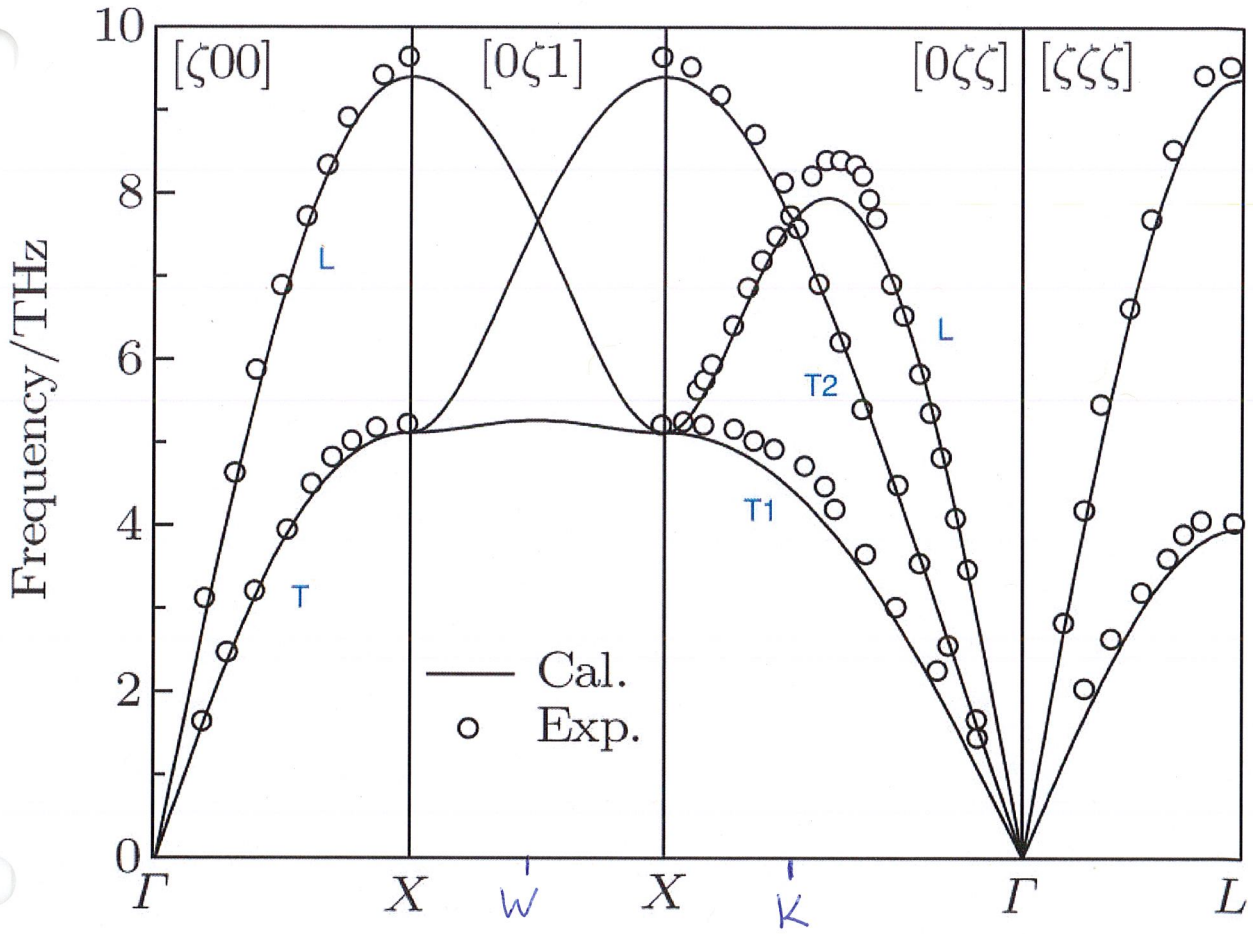
e.g. Monatomic 3D solid



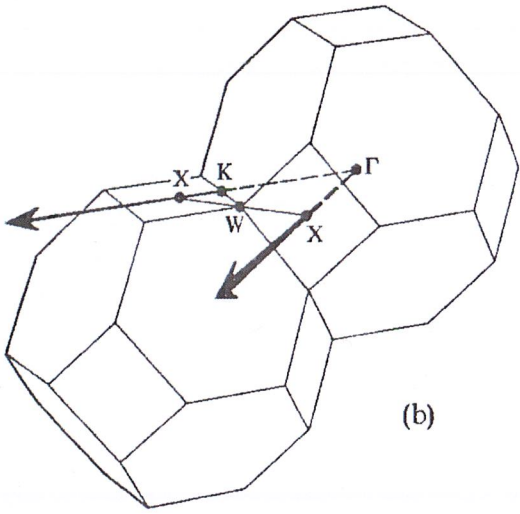
\rightarrow of course, depending on the symmetry of the solid, some dispersion curves may be degenerate!

e.g. Diatomic 3D solid

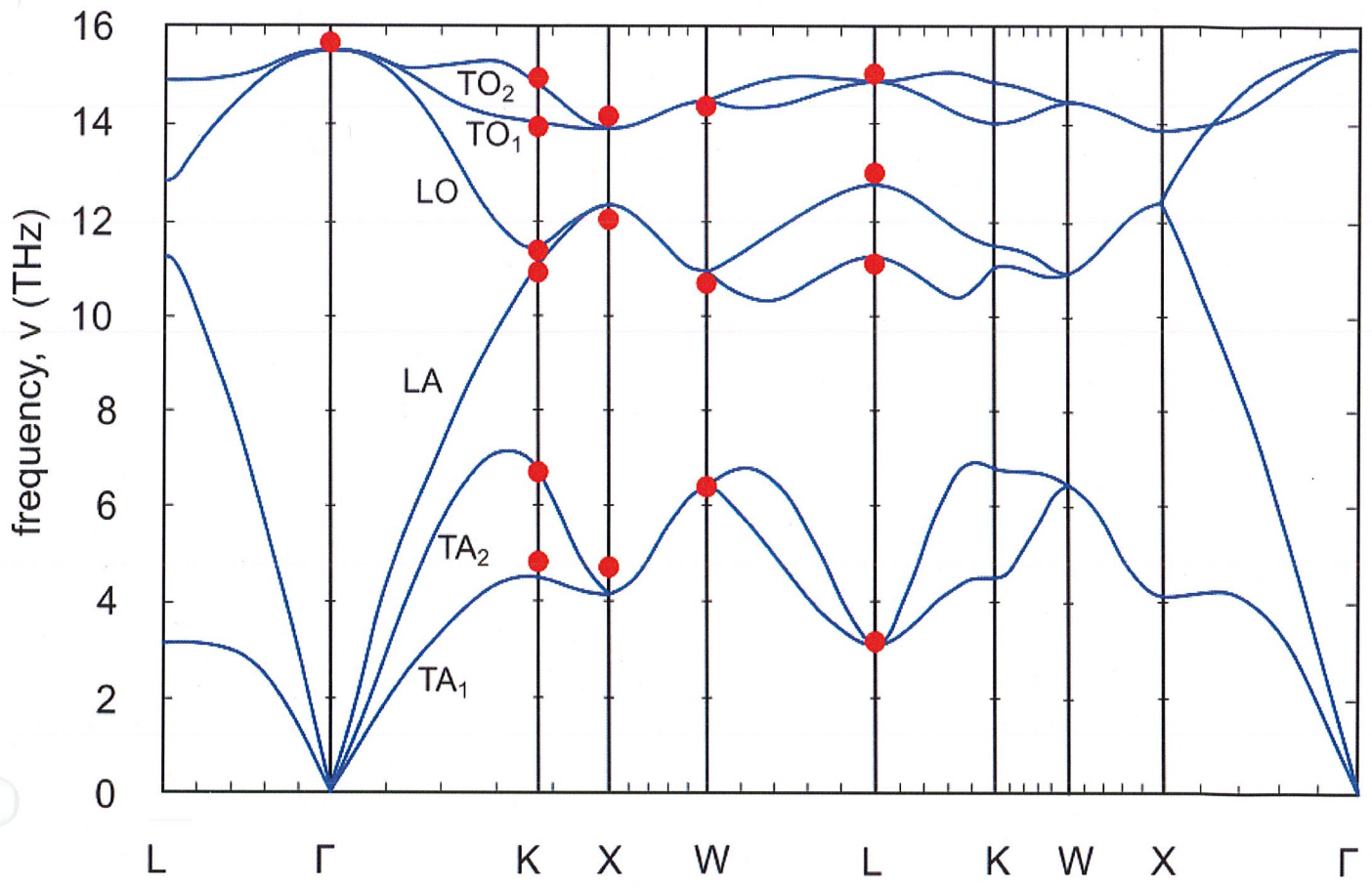




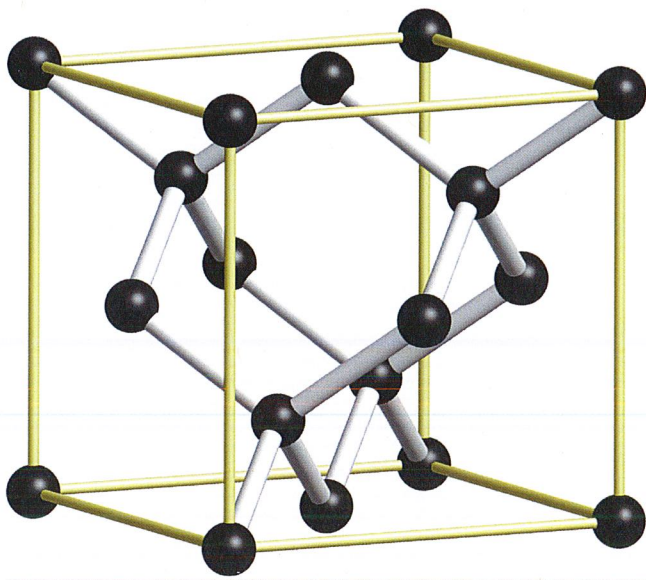
Aluminum



Silicon (crystalline)



FCC structure, 2-atom basis



2-atom basis

→ Masses equal
($M_1 = M_2$)

→ Interaction (Force constants)
not equal

